LAYOUT AND DESIGN OF SPECIAL PURPOSE MACHINE FOR FLAT WORKPIECE SLITTING

ROHIT LAVATE¹, DR. D.N RAUT²

¹²Virmata Jijabai Technological Institute, Mumbai University, Maharashtra, India

ABSTRACT: To increase the productivity and to overcome shortage of skill labor, most of the manufacturing industries are going for automation. The objective of this project is to reduce the cycle time by replacing manual cutting by special purpose machine (SPM) for slitting operation. The concept is that the component having different size and thickness are having complexity on it after casting process we cut those flat surfaces by using slitting machine. The cutting operation performed by workers manually earlier but due to large number of quantity it takes so much of time. This paper gives the overview of layout & design of special purpose machine

Key Words: SPM, Slitting, Conventional tool, Layout, Clamping, Design

INTRODUCTION

The Over the past century, manufacturing has made significant impact progress. New machine tools, high performance cutting tools, and modern manufacturing processes enable today’s industries to make parts faster and better than ever before. Special purpose machine is part of multi-tasking machine. This is new approach to increase the productivity of industry and manpower. If we compare between ordinary machine and special purpose machine in terms of time, costs, number of steps involved, etc. The multi-tasking machine is preferred choice. Technology of SPM is decided upon the principles of cost reduction, increased productivity and optimized safety, better safety etc., which posses with high initial capital; more maintenance cost etc., special purpose machine is part of multi-tasking machine. This is new approach to improve the productivity of organization. If we compare between ordinary machine and special purpose machine in terms of time, costs, number of steps involved, etc. The multi-tasking machine is first choice. SPM is higher degree mechanism in which human involvement is replaced by mechanical, electrical, fluid power technologies capable of doing physical.

METHODOLOGY:-

1. Define the Problem
2. Do Background Research
3. Specify Requirements
4. Brainstorm Solutions
5. Choose the Best Solution

MACHINE LAYOUT

1. MACHINE BED:

Machine Bed acts as housing for every element of machine. It absorbs the vibrations and shocks produced during the machining process. It should be rigid enough to handle. The bed is a strong base that connects to the headstock and permits the tailstock and carriage to be moved parallel to the spindle axis. This is smoothen by hardened and ground bed ways which restrain the carriage and tailstock in a set track.

Fig.2: Machine Bed

2. CUTTER AND POWER TRANSMISSION SYSTEM

The power is transmitted from motor to the spindle assembly through the transmitters. It is an mutually joined linked system of shafts, gears and other electrical parts that form a bridge to transfer power and energy. The oldest type of the transmission system is the manual transmission which has undergone several
changes and alterations to form the present day transmission system of automated nature.

There are different types of transmission systems:

- Manually operated
- Semi-automatic
- Fully-automatic
- Continuously variable

We are here selecting here simple power transmission system that contains only Belt motor arrangement. It contains following parts

- Rotary Shaft
- Belts
- Motor
- Bearing

![Power Transmission System](image)

**Fig.3: Power Transmission System**

3. WORKPIECE PLACEMENT & CLAMMING ARRANGEMENT

Most fixtures have solid elements, attached to the floor or to the body of the machine and considered immovable relative to the motion of the machining bit, and one or more movable components known as clamps. These clamps allow work pieces to be easily hold in the machine or removed, and yet stay safe during operation. Many are also adjustable, permitting for work pieces of different sizes to be used for different operations. Fixtures must be designed such that the pressure or motion of the machining operation is directed primarily against the solid component of the fixture. This reduces the likelihood that the fixture will fail, interrupting the operation and potentially causing damage to infrastructure, components, or operators.

Fixtures may also be produced for very general or simple uses. These multi-use fixtures tend to be very simple themselves, often relying on the precision and obsolete of the operator, as well as surfaces and components already present in the workshop, to provide the same advantages of a specially-designed fixture. Examples include adjustable clamps, workshop vises, and improvised devices such as weights and furniture.

Each component of a fixture is designed for one of two purposes: location or support.

![Work piece Placement](image)

**Fig.4: Work piece Placement**

4. WASTE REMOVAL

The manufacturing region of the product life cycle starts when raw material enters the manufacturing system to be converted to a product. Loss of virgin material during production has a significant environmental impact in terms of

- The quantity of material lost,
- The associated economic price, and
- The environmental risk associated with the lost material.

It is important to point out at here that most forms of wastes are not easy to control. The chips generated in machining contain one such stream of material. Material
losses during production processes occur due to chip formation. Since chip formation is an innate characteristic of machining processes, the production of chips is inevitable.

However the physical form of the material waste stream can be controlled.

Handling and disposal of the chips is dependent on their size, shape and texture. Chip shape influences the amount of cutting fluid carried away. It is more efficiently viable to restore large amount of chips rather than small volumes. Another constraint in restoring is the decay of the stream due to the presence of dissimilar materials. Continuous chips are formed while cutting ductile metals such as steels, copper, iron, and aluminum. Shearing is the main phenomenon included in continuous chip formation. Chip formation takes place in the zone started from the cutting edge to the junction of the work and tool faces. This is called the primary deformation zone.

In case of brittle materials the displacement occurs in the primary deformation zone. This is due to huge strain in the workpiece. Irregular chips thus formed are called discontinuous chips.

5. RAIL SYSTEM/ FEEDING ARRANGEMENT

Cross rail:

The cross rail is installed on the front of the machine body and can be moved up and down. Sliding along the cross rail is a saddle which carries the work table.

Cross ways:

It contains horizontal table sideways which allow the functioning of the table. It is attach with some cross movement mechanism.

Fig. 5: Waste Removal

Fig. 6: Feeding Arrangement

DESIGN OF COMPONENTS:

Size of cutter:

The outside diameter of the cutter D depends upon the arbor diameter, d, and thickness of the cutter ring, t, and the height of the cutting tooth, h, or the depth of the flute.

It is given as:

\[ D = d + 2t + 2h \]

Generally the cutter diameter, D, is taken about 2.5 to 3 times the arbor diameter.

The face width of the cutter should be adequate so as to give sufficient support to the cutting edges.

Cutter hub diameter = \( d + 2 \times \text{thickness of body} \) = \((1.5 \text{ to } 2.5) \times d\)

Diameter of plain milling cutters and the depth of cut are also interred related as follows:

\[ D = 60 \text{ to } 90 \text{ mm for depth of cut up to } 5 \text{ mm} \]

= \( 90 \text{ to } 110 \text{ mm for depth of cut up to } 8 \text{ mm} \)

= \( 110 \text{ to } 150 \text{ mm for depth of cut up to } 12 \text{ mm} \)
As size of the work piece is uneven and depth of cut is supposed to be maximum so we chose carbide cutter - 150 mm.

Number of teeth depends upon size of work piece. (Coarser, finer)

**Selection of pulley diameters (d and D):**

For power given select small pulley diameter (d) from V-Belt. then using the speed ratio, calculate the larger pulley diameter (D).

Speed ratio = D/d = N₁/N₂

As we required to keep same speed as motor we are taking speed ratio as 1 Larger pulley diameter, D = Speed ratio \times d

Diameter of both the pulleys is 80mm

**Approach Length of Cutter:**

\[ AP = \sqrt{d (D-d)} \]

\[ d = \text{Depth of cut} = 12 \text{mm} \]

\[ D = \text{Diameter of cutter} = 150 \text{ mm} \]

\[ AP = \sqrt{(12(150-12))} \]

\[ AP = 41 \text{mm} \]

**Slitting Time = (L+A)/f**

\[ f = \text{feed rate} = 0.1 \text{ mm/sec} \]

\[ = (20+41)/0.1 \]

\[ = 610 \text{ sec} \]

**MRR = w*d*f**

\[ W = \text{width of cut} = 5 \text{ mm} \]

\[ d = \text{depth of cut} = 12 \text{ mm} \]

Feed rate = 0.1 mm/sec

\[ \text{MRR} = 5*12*0.1 \]

\[ \text{MRR} = 6 \text{ mm}^3/\text{sec} \]

**Force required cutting work piece (F):**

\[ F = \tau * (\text{Shearing Area}) \]

\[ \tau = \text{Shear strength in Mpa} = 70 \text{ Mpa} \]

Shearing Area = (40/120)

\[ F = 233.33 \text{N} \]

**Torque Required (T):**

\[ T = (F \times r) \]

\[ r = \text{radius of cutter} = 75 \text{mm} \]

\[ T = 233.33 \times 0.75 \]

\[ T = 175 \text{ Nm} \]

**Power Required (P) in hp**

\[ P = ((2\pi NT)/60) \]

\[ N = \text{RPM of Cutter} = 720 \text{ RPM} \]

\[ P = 1.3194 \text{ KW} \]

\[ P = 1.5 \text{ HP} \]

Hence 1.5 hp motor is selected

**Selection of Belt:**

![Belt design](image)

\[ \text{Length} = 2C + \frac{\pi(D_1 + D_2)}{2} + \frac{(D_1 - D_2)^2}{4C} \]
C = Center distance of pulley = 475 mm

\( D_1 = \text{ Dia of Pulley at motor } = 31 \text{ mm} \)

\( D_2 = \text{ Dia of Pulley at Shaft / Arbor } = 62 \text{ mm} \)

Length = 1097 mm

Angle of contact (\( \alpha \)) = \((180 - 2\beta)(\pi/180)) \)

\( \sin\beta = (D_1/2C) \)

\( \beta = 1.87^\circ \)

\( \alpha = 3.0731^\circ \)

**Belt Velocity (V)**

\[ V = \left(\pi D_1 N\right)/60 \]

\[ V = 2.36 \text{ m/sec} \]

**Tension in Belt (P₁, P₂)**

\( P_1 = \text{Tension on tight side} \)

\( P_2 = \text{Tension on Slack side} \)

Coefficient of friction (\( \mu \)) = 0.3 for leather

\( P_1/P_2 = e^{\mu\beta} \)

\( P_1 = 2.5118P_2 \)

Power Transmitted = (P₁ − P₂)*V

\( P = 1.3194\text{Kw} \)

\( P_1 = 927.4 \text{ N} \)

\( P_2 = 368.29 \text{ N} \)

**Stress developed in Leather Belt (σ)**

\( \sigma_u = \text{Ultimate tensile stress of leather} = 37.4733 \text{ Mpa} \)

\( \sigma = P_1/(b*t) \)

\( b = \text{breadth of belt} = 13 \text{mm} \)

\( t = \text{thickness of belt} = 8.5 \text{mm} \)

\( \sigma = 8.39 \text{ Mpa} \)

Hence stress generated is less than ultimate strength

Hence safe design

**Forces on Bearings (B₁, B₂):-**

Resolving forces in verticle direction

\( B_1 + B_2 + 234 - 1295 = 0 \)

\( B_1 + B_2 = 1061 \)

Taking Moment about bearing 2

\( 1295*126 - B_1*55 + 234*162 = 0 \)

\( B_1 = 3655.9636 \text{ N} \)

\( B_1 = 3.65 \text{ KN} \)

\( B_2 = -2.59 \text{ KN} \)

**Diameter of Shaft (Dₛ):-**

Yield strength of EN24 = 680Mpa

Factor of Safety = 3

\( D_s = 25 \text{ mm} \)

\( M = 91947 \text{ Nmm} \)

\( \sigma = \frac{32 * M}{\pi d^3} \)

\( \sigma_{actual} = \left(91947*32\right)/(\pi*25^3) \)

\( \sigma_{actual} = 59.94 \text{ Mpa} \)

\( \sigma_{design} = 680/3 \)

\( \sigma_{design} = 226.3 \text{ Mpa} \)

\( \sigma_{actual} \text{ less than } \sigma_{design} \)

Hence it is safe design.

**CONCLUSION**

The design of SPM is will be very useful for small scale industry. There are machine based on cutting flat surfaces but it has demerits like large in size, costly, need skilled labors to operate. But we have our machine which will overcome this demerit by compact size, less cost no need for skilled people. The main aim of this machine is to reduce timing for manual cutting and reduce the efforts. This aim can be achieved by our machine.
Discussion

Once you connect motor to power and power switched on. The motor starts running. Through the belt the power is transmitted to the shaft. The shaft is connected to cutter. The cutter will start rotating. Now with use of clamping system you can clamp the work piece to the rail system.

After clamping work piece you can feed work piece to the cutter. The extra material will get cut and removed through tray runner.

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