Voltage Sag and Harmonics Mitigation Using Distributed Power Flow Controller

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Abstract - According to growth of electricity demand and the increased number of non-linear loads in power grids, providing a high quality electrical power should be considered. In this work, a new power flow controlling device called Distributed Power Flow Controller (DPFC) is presented that offers the same control capability as the UPFC, at a reduced cost and with an increased reliability. The DPFC eliminates the common DC link within the UPFC, to enable the independent operation of the shunt and the series converter. The D-FACTS concept is employed to the series converter to increase the reliability. Multiple low-rating single-phase converters replace the high-rating three-phase series converter, which greatly reduces the cost and increases the reliability. The active power that is exchanged through the common DC link in the UPFC is now transferred through the transmission line at the 3rd harmonic frequency. Depending upon the growth of electricity demand the problem of harmonics and voltage sag is occurred. DPFC is used to mitigate the voltage deviation and improve power quality. Application of DPFC in power quality enhancement is simulated in MATLAB/Simulink environment. In this work three different types of fault analysis (L-G fault, L-L fault and L-L-L-G fault) is done to validate the DPFC ability to improve the power quality.

Keywords- Power flow control, harmonics, voltage sag mitigation, Distributed power flow controller.

1. INTRODUCTION

Flexible ac Transmission Systems (FACTS) devices are used to control power flow in the transmission grid to relieve congestion and limit loop flows [1]. All electrical devices are prone to failure or malfunction when exposed to one or more power quality problems [2]. A power quality problem can be defined as any problem is manifested on voltage, current, or frequency deviation that results in power failure [3]. To control power flow, it is necessary to be able to maintain or change line impedances, bus voltage magnitudes, or phase angle differences. To control the power flow UPFC is the most powerful FACTS device, which can simultaneously control all the parameters of the system. The cost of the UPFC is high because UPFC handle the voltages and currents with high rating.

The UPFC is the combination of a static synchronous compensator (STATCOM) and a static synchronous series compensator (SSSC), which are coupled via a common dc link [4]. Due to the common dc-link interconnection, a failure that happens at one converter will influence the whole system, which reduces the reliability of the system. Due to lower reliability and higher cost the UPFC has not been commercially used, even though, it has the most advanced control capabilities.

In this paper, the UPFC is further developed into a new FACTS device that is Distributed Power Flow Controller (DPFC), by applying the two approaches i.e., eliminating the common DC link and distributing the series converter. Within the DPFC, the common dc link between the shunt and series converters is eliminated, which provides flexibility for independent placement of series and shunt converter [5].
Distributed power flow controller having two major advantages over Unified power flow controller: 1) The cost of DPFC is low because of the low component rating of the series converter and low voltage isolation, and 2) The reliability of the DPFC is high due to elimination of d.c. link between series and shunt converters.

In this work, the DPFC is used to mitigate the voltage sag and harmonics in three different cases. Line to ground, Line to line and 3-phase to ground faults are created to establish voltage sag and harmonics in the system and DPFC is used to mitigate both the problem.

2. DPFC CONSTRUCTION

The DPFC is derived from the UPFC by considering two approaches as follows. First, eliminating commonly connected dc link of UPFC [6] and the second is distributing series converter with D-FACTS concept to series converter, which consists of multiple units that are connected in series with the transmission lines as shown in figure.2.

The unique control capability of the UPFC is due to the back-to-back connection between the shunt and series converters, which allows the active power to freely exchange. In DPFC the active power exchange between converters with an eliminated DC link is provided through the transmission line present between the AC ports of the shunt and the series converters.

3. RELATED WORK

Distributed Power Flow Controller developed by eliminating the common DC link and distributing the series converter, which is based upon Distributed static series compensator concept. Both the concepts are explained below.

3.1 Elimination of D.C. link

Within the DPFC, the transmission line is used as a connection between shunt converter output and AC port of series converters, instead of using DC-link for power exchange between converters [7]. The active power exchange in DPFC is based on non-sinusoidal voltage and current, which can presented as the sum of sinusoidal components at different frequencies. It is the main result of Fourier analysis.

Fig - 4: Active power exchange between DPFC converters

The power supply generates the active power and the shunt converter absorbs it in fundamental frequency of current. Meanwhile, the third harmonic component is trapped in Y-Δ transformer [8]. The third harmonic current is injected into the neutral of Δ-Y transformer through the output terminal of the shunt converter. This harmonic current controls the dc voltage of series capacitors. According to the amount of required active power at the fundamental frequency, the DPFC series converters generate a voltage at the harmonic frequency, thereby absorbing the active power from harmonic components. At the receiving end transformer a high pass filter is connected, which is used to blocks the fundamental frequency components and allows the harmonic components to pass. High pass filter provides a return path for the harmonic component.

3.2 Distributed static series compensator

The Distributed Static Series Compensator (DSSC) is a distributed SSSC, which keeps the functionality of the SSSC with a much lower cost and higher reliability. The concept of DSSC uses a large number of units with low power ratings instead of one controller with a large power rating. The configuration of a DSSC unit is shown in Fig.5. This figure shows a single unit of series converter. It is a single-phase converter which is attached to transmission lines by a single-turn transformer. The transmission line acts as secondary winding for single-turn transformer, inserting controllable impedance into the line directly. Costly high
voltage isolation is not required because converters are hanging on the line.

Most of the voltage injected by a DSSC unit is in quadrature with the line current, to emulate inductive or capacitive impedance. A small part of the voltage is in phase with the line current and serves to self-power of DSSC unit. The DSSC is remotely controlled via wireless communication or a PLC (Power Line Communication). Rating of the device is very low (in the range of 10-20 KVA).

To control the transmission line, number of DSSC devices need to be attached to the line as per the requirement. At the highest level, DSSC can maximize the utilization of asset, reduction in congestion of system, available transfer capacity (ATC) of the system, enhance system reliability and capacity under contingencies, enhance system stability and can do so with lower capital and operating cost than most conventional single-point 'lumped' solutions, such as FACTS devices.

As shown in Fig. 5, Single Turn Transformer (STT) with a NC (normally closed) switch which makes the device in bypass condition until the inverter is activated. The dc control power supply transformer is excited by the current that flows in the STT secondary winding. As the switch is opened, DC bus of the inverter charged up and operation of inverter is initiated.

4. CONTROL STRATEGY OF DPFC

The DPFC system consists of two types of converters, and each type of converter requires a different control scheme. The DPFC has three control strategies: central controller, series control and shunt control. The shunt and series control are local controllers and are responsible for maintaining their own converters parameters.
4.3 Shunt control

The shunt converter is controlled to inject a constant 3rd harmonic current into the transmission line, which is intended to supply active power for the series converters. The shunt converter extracts some active power from the grid at the fundamental frequency to maintain its dc voltage.

The dc voltage of the shunt converter is controlled by the $d$ component of the current at the fundamental frequency, and the $q$ component is utilized for reactive power compensation. The series converters generate a voltage with controllable phase angle at fundamental frequency, and use the voltage at the 3rd frequency to absorb active power to maintain its dc voltages at a constant value. The power flow control function is realized by an outer control loop, the power flow control block. This block gets its reference signals from the system operator, and the control signals for DPFC series converters are sent remotely via wireless or PLC communication method.

5. SIMULATION

The simulation of the DPFC has been done in Matlab/simulink environment, which is shown in Fig. 9. The DPFC model is simulated with a three phase source, which is connected to a non-linear load. The three phase source is connected to the load through parallel transmission lines(line 1 and line 2) with the same length. The series converter of DPFC is distributed through the line 2 and the shunt converter of DPFC is connected to the line 2 and ground through a Y-Δ three-phase transformer. For examine the performance of DPFC, a fault is created near the load. The result analysis have been done in three different cases. In case 1 single line to ground fault is considered, in case 2 line to line fault is considered and in case 3 three phase to ground fault is considered. The time duration of fault is 0.1 seconds (200-300 millisecond). The simulation parameters is listed in table 4.

6. SIMULATION RESULTS AND DISCUSSION

Case-A: Single line to ground fault

![Fig-9: Simulation model of DPFC](image)

![Fig-10: Load voltage waveform without DPFC](image)

![Fig-11: Load voltage THD without DPFC](image)
Fig - 12: Load voltage waveform with DPFC

Fig - 13: Load voltage THD with DPFC
Case-B: Line to line fault

Fig - 14: Load voltage waveform without DPFC

Fig - 15: Load voltage THD without DPFC

Fig - 16: Load voltage waveform with DPFC

Fig - 17: Load voltage THD with DPFC
Case-C: Three phase to ground fault

Fig - 18: Load voltage waveform without DPFC

Fig - 19: Load voltage THD without DPFC
7. COMPARATIVE ANALYSIS OF RESULT

When any type of fault is occurred in the transmission line then parameters of the line gets affected. During fault condition the problem of voltage sag, current and increase in harmonics occurred. Without using any compensation these problems will remains in the system. After implementation of DPFC in the system the above problems are mitigated. The comparative analysis is done on the following three cases.

### Table -1: Comparative analysis for single line to ground fault

<table>
<thead>
<tr>
<th>Phases</th>
<th>Without DPFC (THD)</th>
<th>Voltage sag</th>
<th>With DPFC (THD)</th>
<th>Voltage sag</th>
</tr>
</thead>
<tbody>
<tr>
<td>Phase A</td>
<td>3.18 %</td>
<td>0.50 P.U.</td>
<td>Nominal</td>
<td>Nominal</td>
</tr>
<tr>
<td>Phase B</td>
<td>0.75 P.U.</td>
<td>0.25 P.U.</td>
<td>Nominal</td>
<td>Nominal</td>
</tr>
<tr>
<td>Phase C</td>
<td>Nominal</td>
<td>Nominal</td>
<td>Nominal</td>
<td>Nominal</td>
</tr>
</tbody>
</table>

### Table -2: Comparative analysis for line to line fault

<table>
<thead>
<tr>
<th>Phases</th>
<th>Without DPFC (THD)</th>
<th>Voltage sag</th>
<th>With DPFC (THD)</th>
<th>Voltage sag</th>
</tr>
</thead>
<tbody>
<tr>
<td>Phase A</td>
<td>0.60 P.U.</td>
<td>Nominal</td>
<td>Nominal</td>
<td>Nominal</td>
</tr>
</tbody>
</table>

### Table -3: Comparative analysis for three phase to ground fault

<table>
<thead>
<tr>
<th>Phases</th>
<th>Total harmonics distortion (THD)</th>
<th>Voltage sag</th>
<th>With DPFC Total harmonics distortion (THD)</th>
<th>Voltage sag</th>
</tr>
</thead>
<tbody>
<tr>
<td>Without DPFC</td>
<td>6.28 %</td>
<td>0.35 P.U.</td>
<td>With DPFC</td>
<td>0.69 %</td>
</tr>
<tr>
<td>With DPFC</td>
<td>Nominal</td>
<td>Nominal</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

8. CONCLUSIONS

In this study, the application of DPFC as a new FACTS device, in the voltage sag mitigation of a system composed of a three-phase source connected to a non-linear load through the parallel transmission lines is simulated in Matlab/Simulink environment. The voltage dip is analyzed by implementing a fault close to the system load. To detect the voltage sags and determine the three single phase reference voltages of DPFC, the SRF method is used as a detection and determination method. The obtained simulation results show the effectiveness of DPFC in power quality enhancement, especially in sag mitigation. In this work the performance analysis of the distributed power flow controller is done in three different cases as below-

- **Case-A: Single line to ground fault**
  - In this work, single phase to ground fault is created with the help of MATLAB. When DPFC is not connected with the transmission line then the value of voltage sag is 0.5 per unit in phase A, which is completely mitigated when DPFC is connected with the transmission line.
  - Total harmonics distortion (THD) is also reduced from 3.18% to 0.25% in line.
  - The voltage sag in this case is 50% of the nominal voltage.

- **Case-B: Line to line fault**
  - In this work, line to line fault is created with the help of MATLAB. When DPFC is not connected with the transmission line then the value of voltage sag is 0.6 per unit in phase A and 0.35 per unit in phase B, which is completely mitigated when DPFC is connected with the transmission line.
In this case total harmonics distortion (THD) is also reduced from 6.28% to 0.69% in line.

Case-C: Three phase to ground fault

- In this work, three phase to ground fault is created with the help of MATLAB. When DPFC is not connected with the transmission line then the value of voltage sag is 0.4 per unit in all the phases, Which is completely mitigated when DPFC is connected with the transmission line.
- In this case total harmonics distortion (THD) is also reduced from 6.28% to 0.68% in line.

Table - 4: System Parameters

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Rating</th>
</tr>
</thead>
<tbody>
<tr>
<td>Source voltage</td>
<td>230 KV</td>
</tr>
<tr>
<td>Frequency</td>
<td>60 Hz</td>
</tr>
<tr>
<td>X/R</td>
<td>3</td>
</tr>
<tr>
<td>Transformer rating</td>
<td>100 MVA</td>
</tr>
<tr>
<td>Magnetization resistance</td>
<td>500 (P.U)</td>
</tr>
<tr>
<td>Magnetization inductance</td>
<td>500 (P.U)</td>
</tr>
<tr>
<td>Resistance per unit length of line</td>
<td>0.01273</td>
</tr>
<tr>
<td>Inductance per unit length of line</td>
<td>0.9337 mH</td>
</tr>
<tr>
<td>Capacitance per unit length of line</td>
<td>12.74 nF</td>
</tr>
<tr>
<td>Length of line</td>
<td>100 Km</td>
</tr>
<tr>
<td>Snubber resistance</td>
<td>10^6 ohm</td>
</tr>
<tr>
<td>D.C link capacitance</td>
<td>25 x 10^-3</td>
</tr>
<tr>
<td>Ground resistance</td>
<td>0.001 ohm</td>
</tr>
</tbody>
</table>

REFERENCES


BIOGRAPHIES

Vikash Kumar Goutam received his B. Tech. degree in Electrical Engineering from MPEC Kanpur in 2006. Presently he is pursuing his M.Tech in Electrical Engineering (Power system) from KNIT, Sultanpur India.

Dr. Deependra Singh is currently working as a Professor in Electrical Engineering department in KNIT, Sultanpur, India. His area of interest is Measurement & Instrumentation, Power Systems, and Distributed Generation.