

CAPACITORLESS LDO FOR HIGH FREQUENCY APPLICATIONS

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Abstract – Power saving is important in all portable electronic devices like cellular phones and PDAs. This is essential to reduce the standby power and improve the battery runtime. Single stage regulator topologies are mainly used in embedded applications because of low power consumption. A single stage and adaptive biased low-dropout regulator is used to achieve a comparable dc load regulation. This is done mainly by modifying the adaptive bias loop which improves both the differential mode signals as well as common-mode signals. In addition, the proposed regulator is stable for a wide range of logics with variable capacitors and also for the capacitor-less conditions. The proposed regulator is implemented in a standard 0.18- μm CMOS technology.

The advantages of low dropout voltage regulator DC to DC regulators include the absence of switching noise, device size is small, and design simplicity is greater.

Key Words: Low Drop-Out (LDO) regulator, Adaptive biasing, Single Stage Regulator, CMOS Technology, Load Regulation.

1. INTRODUCTION

A low-dropout (LDO) regulator is providing a clean supply due to low noise, ripple-free characteristics and less area. LDO regulator is used to supply a high load current demand, for a major challenge to maintain the dc accuracy of the output voltage. In electronics circuits, the dropout voltage of a regulator is the difference between the output voltage and input voltage. Dropout voltage for a general purpose integrated circuit regulator can high as 2 Volt, but low dropout regulators have a dropout of less than 100 mV at full load of the circuit. The load is very depending on the load for the dropout voltage in the regulator. Higher load will increasing usually, due to the regulator's pass transistor and circuitry of the internal resistance. Dropout voltage varies to temperature is varied. Dropout voltage is specified range of temperatures as well as load. Determine the efficiency of the voltage regulator in the Dropout voltage and quiescent current. Dropout voltage is low due to improve efficiency. A low-dropout is mean DC linear voltage regulator that can regulate the output voltage even when the supply voltage is very close to the output voltage is called low dropout or LDO regulator.

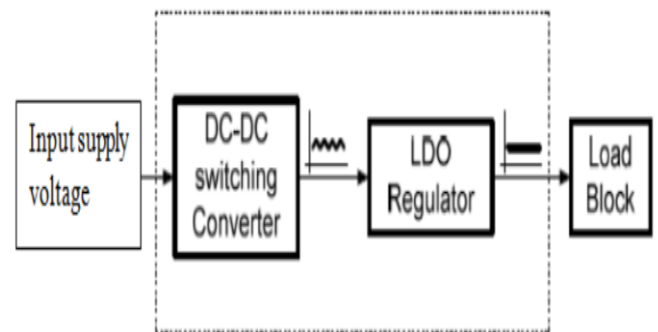


Fig -1: General LDO Regulator

The general LDO regulator is the Input supply voltage to given as the DC-DC Switching Converter is the analog waveform to the LDO Regulator is the Digital waveform to the load is Block.

2. CONVENTIONAL SINGLE STAGE AB- LDO TOPOLOGIES

2.1 Topology-1 (Differential Feedback Amplifier)

In operational Tran's conductance amplifier is the voltage is applied across the inputs of the currents I_1 and I_2 become different. The amplifier of the bias current is made signal dependent by adding an additional current source to the tail current source for realize A. "A" is the current feedback factor. The currents at the input is subtract are provided on the current mirrors, it is define a differential feedback amplifier. In the differential feedback amplifier is the large number of transistors are used.

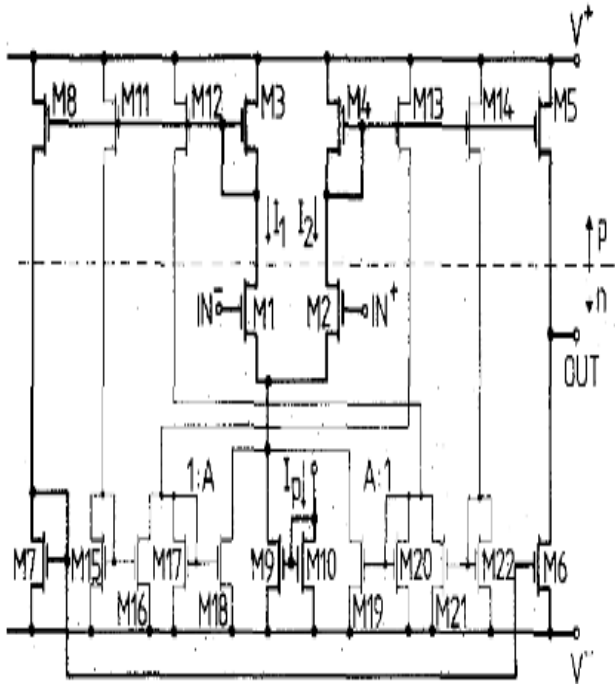


Fig -2: Differential feedback amplifier

2.2 Direct Feedback Amplifier

The direct feedback amplifier is used as a micro power buffer for large capacitive loads. The design is nearly the whole supply current is used to charge the load capacitor. The Fig -3 represents the amplifier. Split up in the amplifier is two symmetrical parts. the current of the branch is directly fed back to the tail current source in each input stage.

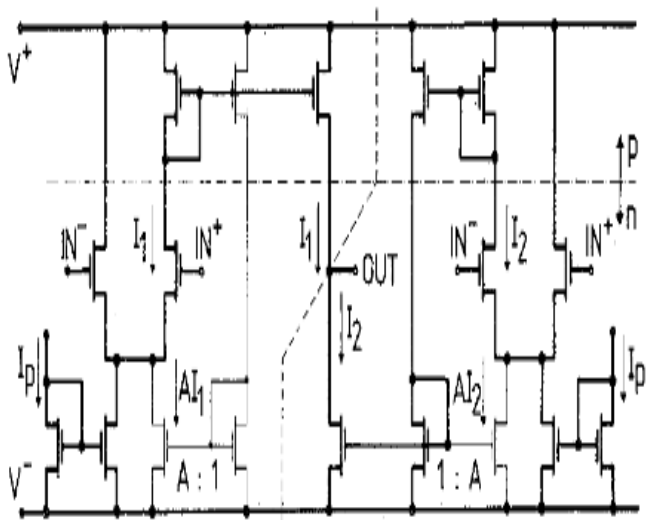


Fig -3: Direct feedback amplifier

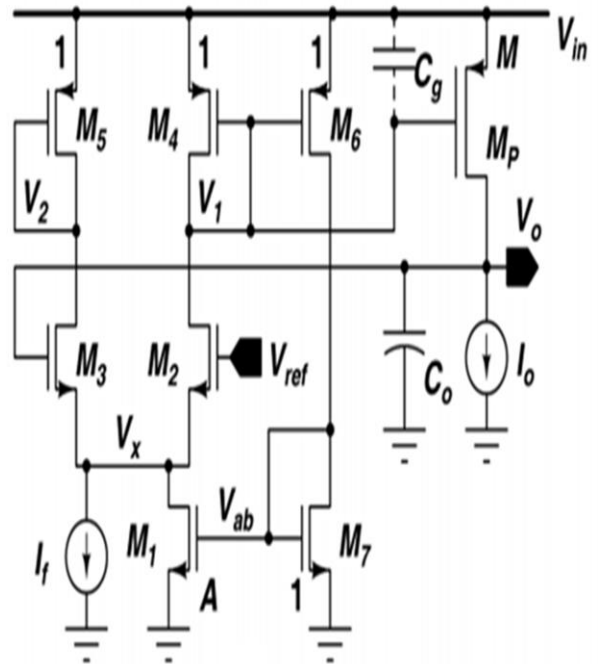


Fig -4: Single stage AB-LDO regulator in topology 1

Single stage AB-LDO regulator in topology 1 is the output current is given as,

$$I_0 = M_1 I_2 = M_1 I_4$$

The M_4 and M_p is mismatch of the current mirror is ignored. To limited differential gain to increase I_1 for the ABL of the input offset is week mechanism.

2.3 Topology- 2

The main differential pair transistors M_1 and M_2 generate an error signal during normal negative feedback operation. The generated error signal is used to bias the tail current M_0 effectively through the loop of transistors involving M_6 , M_7 , M_8 , and M_9 . At steady state, there is no current flowing into the capacitor C_c and it holds the required bias voltage at the gate of the tail-current source. Within the loop, when we go through the path1 whose transistors include M_0 , M_1 , M_3 , and M_6 , we have a positive feedback loop. However, for the path2 transistors M_0 , M_2 , M_4 , M_7 , M_8 , and M_9 , we have a negative feedback loop. The load current is increases of I_0 and the error voltage is increased of I_1 . When compared in topology-1 its better load regulation of the topology-2 for the load current is same.

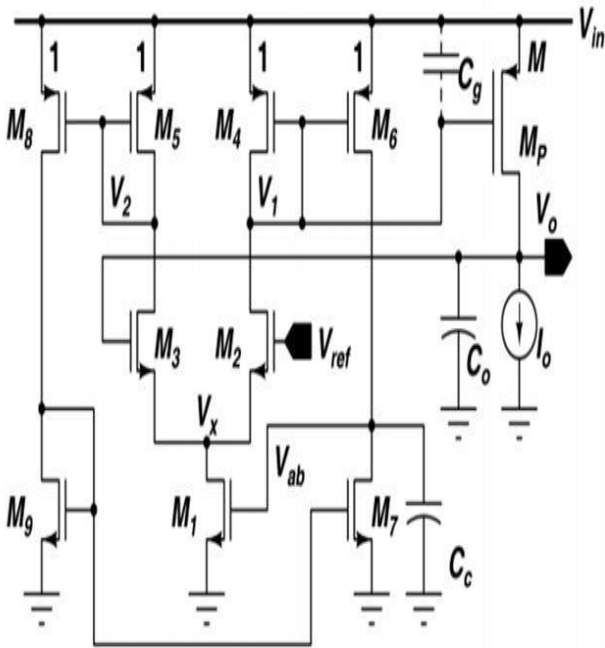


Fig- 5: Single stage AB-LDO regulator topology 2

3. PROPOSED REGULATOR

Each of M_4 and M_5 are two parts, such as (M_{4a}, M_{4b}) and (M_{5a}, M_{5b}) . A cross-coupled configuration is the transistor pair $M_{4b}-M_{5b}$ is connected, as shown in Fig -6. The width of the ratios between $M_{4a}-M_{4b}$ and $M_{5a}-M_{5b}$ pairs is $1: \beta$, the amplifier operation is $\beta < 1$. The cross-coupled pair is used for the multistage comparator design to the differential gain using a fixed-bias scheme is enhanced. In a single-stage configuration, when the cross coupled pair is combined with adaptive biasing, the operation is altered uniquely. The proposed ABL offers a few advantages. First, the variables of width ratio is A and β of the transistors and they are independent of I_0 . Due to these reasons are given by, the regulator of dc operating point alters during large load change as the factor $A \cdot I_2$ changes it is proportionally with I_0 . This factor is maintain the dc accuracy of V_0 during a large load change. A small error is present due to the inequality. A dc operating point of the differential operation is correct the error. Dc accuracy is increased in the regulator. I_1 is the combination of the currents are common mode as well as differential modes of operation, the magnitude of the latter one need not be very high in Topology-2.

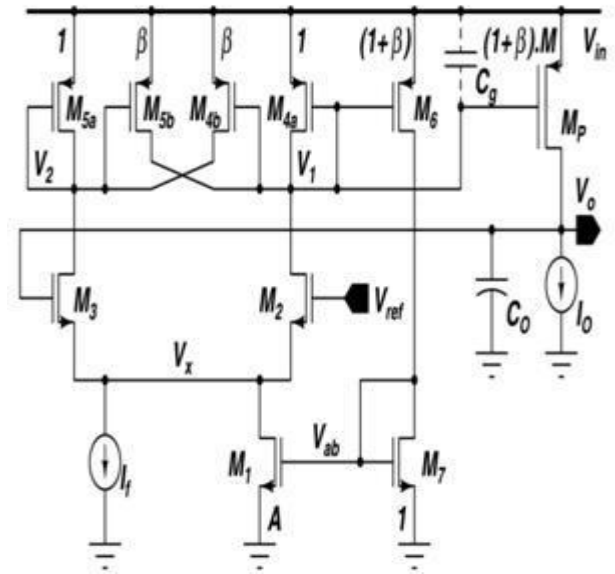


Fig-6: Proposed regulator architecture

4. SIMULATION RESULT

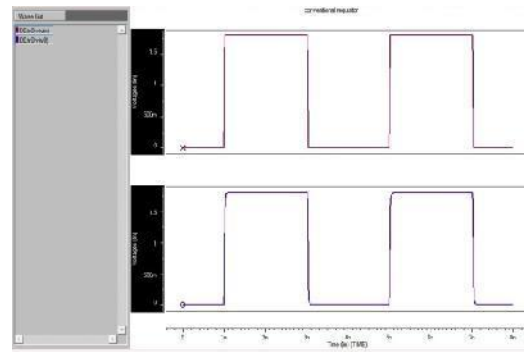


Fig-7: Differential feedback amplifier in with capacitor

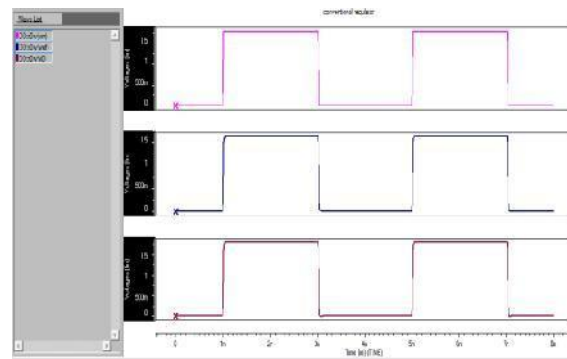


Fig-8: Differential feedback amplifier in without capacitor

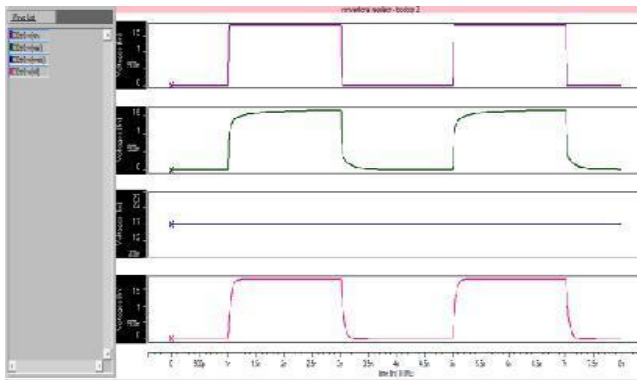


Fig -9: Direct feedback amplifier in with capacitor

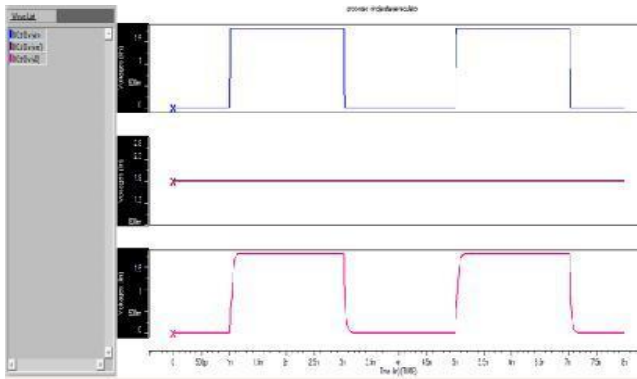


Fig -10: Direct feedback amplifier in without capacitor

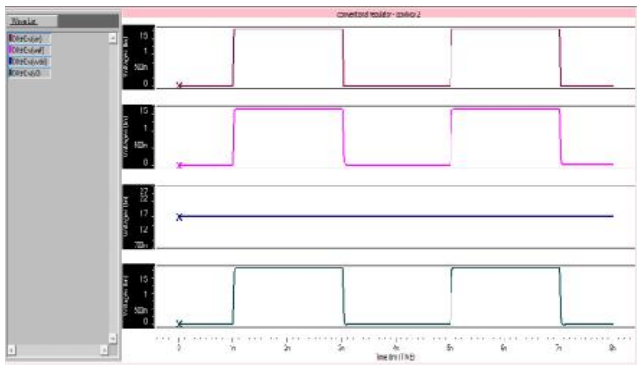


Fig -11: Single stage with capacitor

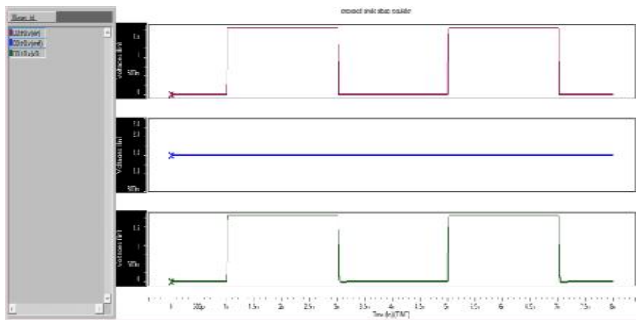


Fig-12: Single stage without capacitor

Table -1: COMPARITIVE ANALYSIS

CIRCUIT	RISE TIME (pS)	FALL TIME (pS)	DELAY (nS)	POWER (mW)	PDP(pJ)
TOPOLOGY1 (WITH CAPACITOR)	0.25	0.26	2.03	4.46	9.07
(WITHOUT CAPACITOR)	0.19	0.21	2.03	4.35	8.84
TOPOLOGY 2(WITH CAPACITOR)	0.88	0.88	2.06	6.77	1.40
(WITHOUT CAPACITOR)	0.19	0.21	2.03	4.71	9.58
PROPOSED (WITH CAPACITOR)	0.77	0.65	2.05	1.14	2.33
(WITHOUT CAPACITOR)	0.17	0.19	2.03	0.98	2.01

5. CONCLUSION

Conventional single stage adaptive biasing low dropout regulator and proposed regulator in with and without capacitor was designed and implemented by using 180nm CMOS technology and simulated using HSPICE simulator. Thus the regulator that consumes low power, low delay and power delay product was designed and rise time, fall time were calculated. Finally results were compared with the existing systems.

6. REFERENCES

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